

Lecture 1: Spaces of norms and GIT

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Growth of convex functions

- If $f: \mathbb{R}_+ \rightarrow \mathbb{R}$ is convex, then either $f(t) \geq \delta t - C$ with $\delta, C > 0$, or f is nonincreasing.
- Let (X, d) be a complete metric space. A **geodesic** $(x_t)_{t \in I}$ of constant speed $c \geq 0$ satisfies $d(x_s, x_t) = c|s - t|$. It is a **geodesic segment** if $I = [a, b]$, and a **geodesic ray** if $I = \mathbb{R}_+$.
- Suppose (X, d) is a **geodesic space** (i.e. any two points are connected by a geodesic segment). By Hopf–Rinow, X is locally compact iff each closed ball B is compact.

Theorem

Suppose $f: X \rightarrow \mathbb{R} \cup \{+\infty\}$ is **convex on geodesics** and **strongly lsc**, i.e. $B \cap \{f \leq c\}$ is compact for each closed ball B and $c \in \mathbb{R}$. For any $x_0 \in X$, one of the following holds:

- either f is **coercive**, i.e. $f \geq \delta d(\cdot, x_0) - C$ for some $\delta, C > 0$;
- or there exists a geodesic ray emanating from $x_0 \in X$ along which f is **nonincreasing**.

Further, (i) implies that f admits a minimizer, and the converse holds if the minimizer is unique.

Proof

- Assume (i) fails, and pick a sequence (x_j) such that $f(x_j) \leq \delta_j d(x_j, x_0) - C_j$ with $\delta_j \rightarrow 0$ and $C_j \rightarrow +\infty$.
- (x_j) unbounded, otherwise $f(x_j) \rightarrow -\infty$, while f strongly lsc implies bounded below on balls \implies may assume $T_j := d(x_j, x_0) \rightarrow +\infty$.
- Pick a unit-speed geodesic $(x_{j,t})_{t \in [0, T_j]}$ joining x_0 to x_j .
- By convexity, $f(x_{j,t}) - f(x_0) \leq \frac{t}{T_j} (f(x_j) - f(x_0)) \leq \delta_j t$
 $\implies (x_{j,t})_{t \in [0, T]}$ stays in compact set $B(x_0, T) \cap \{f \leq C_T\}$
 \implies can assume $(x_{j,t})$ converges on compact sets to a unit-speed geodesic ray $(x_t)_{t \in [0, +\infty)}$ (Arzelà-Ascoli);
- f lsc $\implies f(x_t) \leq f(x_0)$, hence (ii).
- (i) \implies any minimizing sequence is bounded \implies stays in compact set $B \cap \{f \leq c\} \implies$ limit point is a minimizer.
- If x_0 unique minimizer of f , then (ii) cannot hold, hence (i) does.

Busemann convexity and the asymptotic cone

Assume (X, d) complete geodesic metric space.

- The space (X, d) is **Busemann convex** if d is convex on geodesics, i.e. $t \mapsto d(x_t, y_t)$ is convex for any pair of geodesics $(x_t), (y_t)$.
- This is a **nonpositive curvature** condition: suffices to consider geodesic segments with same origin, and convexity is then a sub-Thales' theorem.
- Busemann convexity \implies uniqueness and continuity of geodesics segments with respect to end-points $\implies X$ contractible.
- The **asymptotic cone** (\hat{X}, \hat{d}) is defined as the set \hat{X} of (constant-speed) geodesic rays $\hat{x} = (x_t)$ modulo parallelism (bounded distance), endowed with the metric

$$\hat{d}(\hat{x}, \hat{y}) := \lim_{t \rightarrow +\infty} \frac{1}{t} d(x_t, y_t).$$

- (\hat{X}, \hat{d}) is also geodesic and complete, and \hat{X} is in 1–1 correspondence with rays emanating from any given base point.

Busemann convexity and the asymptotic cone

- Assume $f: X \rightarrow \mathbb{R} \cup \{+\infty\}$ is convex and lsc, and pick $x_0 \in X$ with $f(x_0) < \infty$. Then $\hat{f}: \hat{X} \rightarrow \mathbb{R} \cup \{+\infty\}$ defined by

$$\hat{f}(\hat{x}) := \lim_{t \rightarrow +\infty} \frac{1}{t} f(x_t)$$

is independent of x_0 , convex, lsc.

- If f is strongly lsc, then theorem yields f coercive $\Leftrightarrow \hat{f}$ coercive.
- All of the above holds when geodesics are restricted to a **distinguished class** \mathcal{G} , closed under affine reparametrization and pointwise limits.

Example

Assume (X, d) is normed vector space. Then:

- (X, d) is Busemann convex with respect to class \mathcal{G} of affine geodesics;
- $(\hat{X}, \hat{d}) = (X, d)$;
- \hat{f} is homogenization of f , i.e. smallest convex homogeneous function above f .

The space of norms

Fix a complex vector space $V \simeq \mathbb{C}^d$.

- Denote by $\mathcal{N} = \mathcal{N}(V)$ the set of all norms $\chi: V \rightarrow \mathbb{R}_+$. Natural metric

$$d_\infty(\chi, \chi') := \log \inf\{C \geq 1 \mid C^{-1}\chi \leq \chi' \leq C\chi\} = \sup_{V \setminus \{0\}} |\log \chi - \log \chi'|.$$

- (\mathcal{N}, d_∞) is complete and locally compact. Topology = pointwise convergence on V .
- Denote by $\mathcal{H} \subset \mathcal{N}$ the subspace of Hermitian norms. It is closed (parallelogram identity), and hence (\mathcal{H}, d_∞) complete and locally compact.
- Choice of $\chi \in \mathcal{H}$ yields canonical isomorphisms

$$\mathcal{H} \simeq \text{Herm}^+(V, \chi) \quad \mathcal{H} \simeq \text{GL}(V)/\text{U}(V, \chi).$$

- Any $\chi \in \mathcal{H}$ can be diagonalized in some basis $\mathbf{e} = (e_i)$ of V , i.e.

$$\chi(v)^2 = \sum_i |a_i|^2 \chi(e_i)^2, \quad v = \sum_i a_i e_i.$$

The space of norms

- For any basis \mathbf{e} of V , define the **apartment** $\mathbb{A}_{\mathbf{e}} \subset \mathcal{H}$ as the set of Hermitian norms diagonalized in \mathbf{e} .
- It is closed in \mathcal{H} , and $\chi \mapsto (\log \chi(e_i))_i$ yields isometry $(\mathbb{A}_{\mathbf{e}}, d_{\infty}) \xrightarrow{\sim} (\mathbb{R}^d, \ell^{\infty})$.
- Affine paths in apartments form a distinguished class \mathcal{G} of geodesics in $(\mathcal{H}, d_{\infty})$.
- Any pair of points in \mathcal{H} lies in some common apartment $\mathbb{A}_{\mathbf{e}}$, affine segment between them is independent of \mathbf{e} .
- $(\mathcal{H}, d_{\infty})$ is Busemann convex with respect to \mathcal{G} . More generally:

Theorem (Bhatia, Darvas–Lu–Rubinstein, B–Eriksson)

For any $p \in [1, \infty]$, there exists a unique metric d_p on \mathcal{H} inducing $(\mathbb{A}_{\mathbf{e}}, d_p) \simeq (\mathbb{R}^d, \ell^p)$ for all \mathbf{e} . Furthermore, (\mathcal{H}, d_p) is Busemann convex with respect to \mathcal{G} .

For $p = 2$: $(\mathcal{H}, d_2) \simeq \mathrm{GL}(V)/\mathrm{U}(V)$ as Riemannian symmetric space.

Non-Archimedean norms

- Denote by $|\cdot|_0$ the *trivial absolute value* on \mathbb{C} . Note $|\cdot|_0 = \lim_{\varepsilon \rightarrow 0_+} |\cdot|^\varepsilon$.
- A **non-Archimedean norm** is a function $\chi: V \rightarrow \mathbb{R}_{\geq 0}$ such that
 - ▶ $\chi(v+w) \leq \max\{\chi(v), \chi(w)\}$;
 - ▶ $\chi(av) = |a|_0 \chi(v)$;
 - ▶ $\chi(v) = 0$ iff $v = 0$.

Balls are linear subspaces, and data of χ is equivalent to the filtration $\{\chi \leq R\}_{R \geq 0}$.

- If $\chi = \lim_i \chi_i^{\varepsilon_i}$ pointwise with $\chi_i \in \mathcal{N}(V)$ and $\varepsilon_i \rightarrow 0_+$, then χ is a non-Archimedean (semi)norm.
- Denote by \mathcal{N}^{NA} the set of all non-Archimedean norms χ on V . It is a cone with respect to the scaling action $\mathbb{R}_{>0} \times \mathcal{N}^{\text{NA}} \rightarrow \mathcal{N}^{\text{NA}} \quad (\varepsilon, \chi) \mapsto \chi^\varepsilon$, with apex the trivial norm.
- Can define d_∞^{NA} as before. Then $(\mathcal{N}^{\text{NA}}, d_\infty^{\text{NA}})$ complete, but not locally compact when $d = \dim V > 1$.

Non-Archimedean norms as an asymptotic cone

- any $\chi \in \mathcal{N}^{\text{NA}}$ can be **diagonalized** in some basis $\mathbf{e} = (e_i)$ of V , i.e.
 $\chi(v) = \max_i \chi(a_i e_i) = \max_{a_i \neq 0} \chi(e_i)$ for $v = \sum_i a_i e_i$ (\Leftrightarrow compatible basis for the corresponding filtration).
- **apartment** $(\mathbb{A}_{\mathbf{e}}^{\text{NA}}, d_{\infty}^{\text{NA}}) \simeq (\mathbb{R}^d, \ell^{\infty})$.
- for any $p \in [1, \infty]$, there exists a unique metric d_p^{NA} on \mathcal{N}^{NA} such that $(\mathbb{A}_{\mathbf{e}}^{\text{NA}}, d_p^{\text{NA}}) \simeq (\mathbb{R}^d, \ell^p)$ for all \mathbf{e} .
- $p = 2$, $(\mathcal{N}^{\text{NA}}, d_2)$ Euclidean building.

Theorem

For any affine geodesic ray $\hat{\chi} = (\chi_t)$ in \mathcal{H} , $\chi_{\infty} := \lim_{t \rightarrow \infty} \chi_t^{1/t}$ defines a non-Archimedean norm. Further:

- $\hat{\chi}$ is uniquely determined by χ_0 and χ_{∞} ;
- $\hat{\chi} \mapsto \chi_{\infty}$ induces $(\hat{\mathcal{H}}, \hat{d}_p) \xrightarrow{\sim} (\mathcal{N}^{\text{NA}}, d_p^{\text{NA}})$.

The Hilbert–Mumford criterion

Consider a finite dimensional representation W of $G := \mathrm{GL}(V)$, with maximal compact subgroup $K = \mathrm{U}(V)$.

- A (nonzero) $w \in W$ is **stable** if its G -orbit is closed, with finite stabilizer.
- This holds iff $f: G \rightarrow \mathbb{R}$ defined by $f(g) := \log \|g \cdot w\|$ is proper, for any choice of norm $\|\cdot\|$ on W .
- Choose a K -invariant norm \implies induced function $f: G/K = \mathcal{H} \rightarrow \mathbb{R}$ is **convex** $\implies w$ stable iff $\hat{f} > 0$ on each nontrivial ray in $\hat{\mathcal{H}} \simeq \mathcal{H}^{\mathrm{NA}}$.
- Basis \mathbf{e} of $V \Leftrightarrow$ maximal torus $T \simeq (\mathbb{C}^\times)^d \subset G \Rightarrow$ weight decomposition $W = \bigoplus_{\alpha \in \mathbb{Z}^d} W_\alpha$.
- Write $w = \sum_\alpha w_\alpha$. Then $f(\lambda) = \log \|\sum_\alpha e^{\langle \alpha, \lambda \rangle} w_\alpha\|$ on $\mathbb{A}_\mathbf{e} \simeq \mathbb{R}^d$, hence $\hat{f}(\lambda) = \max_{w_\alpha \neq 0} \langle \alpha, \lambda \rangle$ on $\hat{\mathbb{A}}_\mathbf{e} \simeq \mathbb{R}^d$.
- Conclusion: w is stable iff $\hat{f} > 0$ on $\hat{\mathbb{A}}_\mathbf{e}(\mathbb{Z}) \simeq \mathbb{Z}^d$ for all \mathbf{e} (Hilbert–Mumford criterion).